

# UAV Assisted Energy Delivery

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## Summary

### Problem Statement

Devices are being added that need power; however, there are few energy connections available to power these devices. We need to develop a flexible way to power these devices.

### Solution

- Use a drone to reach these isolated devices
- The drone will fly autonomously to destination
- Detection of device by QR code and color recognition
- Transfer energy from drone to isolated device

### Standards

- 1028-2008 Software Audits
- 1625-2008 Multicell Batteries
- 16085-2006 Risk Management
- 14764-2004 Software Lifecycle Processes and Maintenance



## Design Requirements

### Functional

- Take off, fly to / from a specified location autonomously
- Dock with docking node for power transfer autonomously
- Deliver power to / from payload battery to docking node

### Non-Functional

- Scalability (up to miles)
- Security
- Performance (wind resistance, flight efficiency)

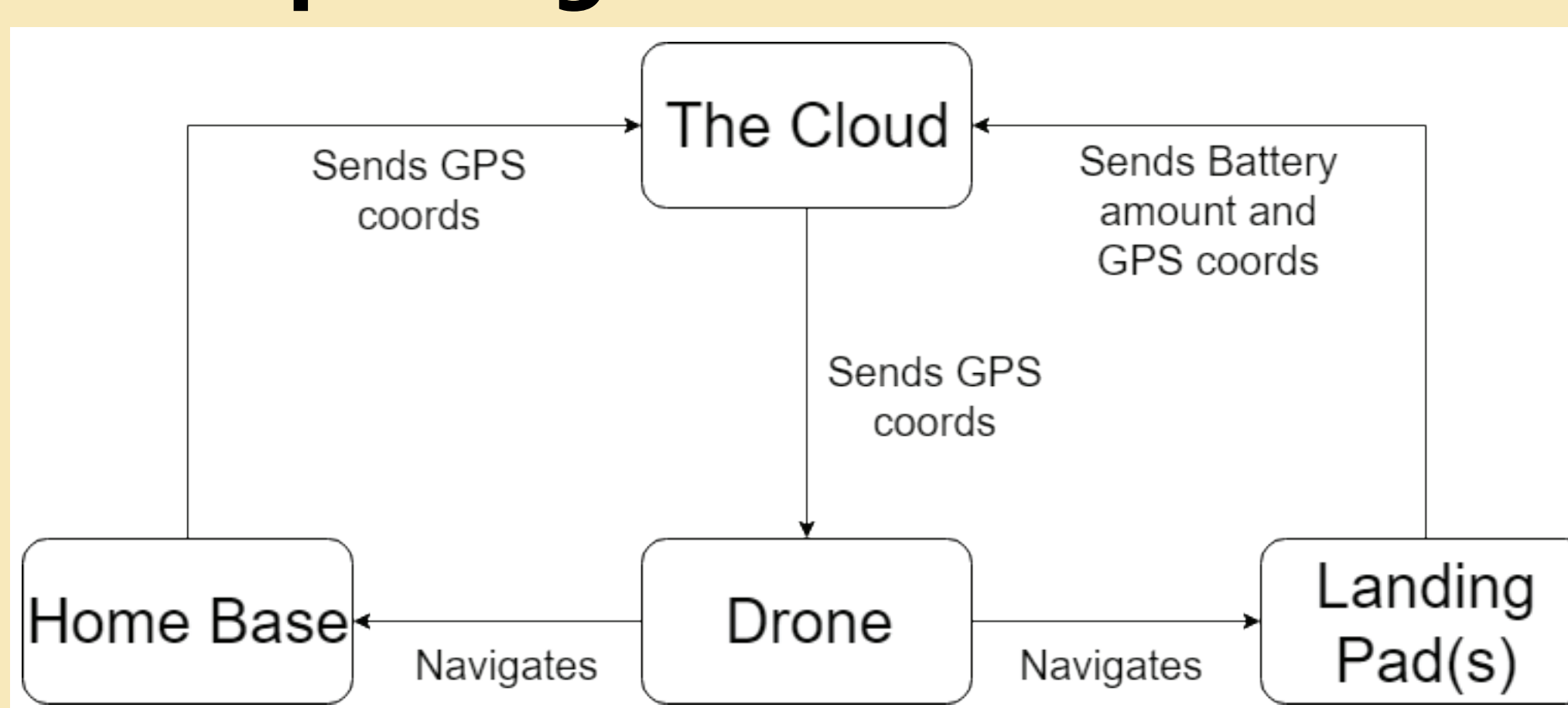


### Acknowledgements

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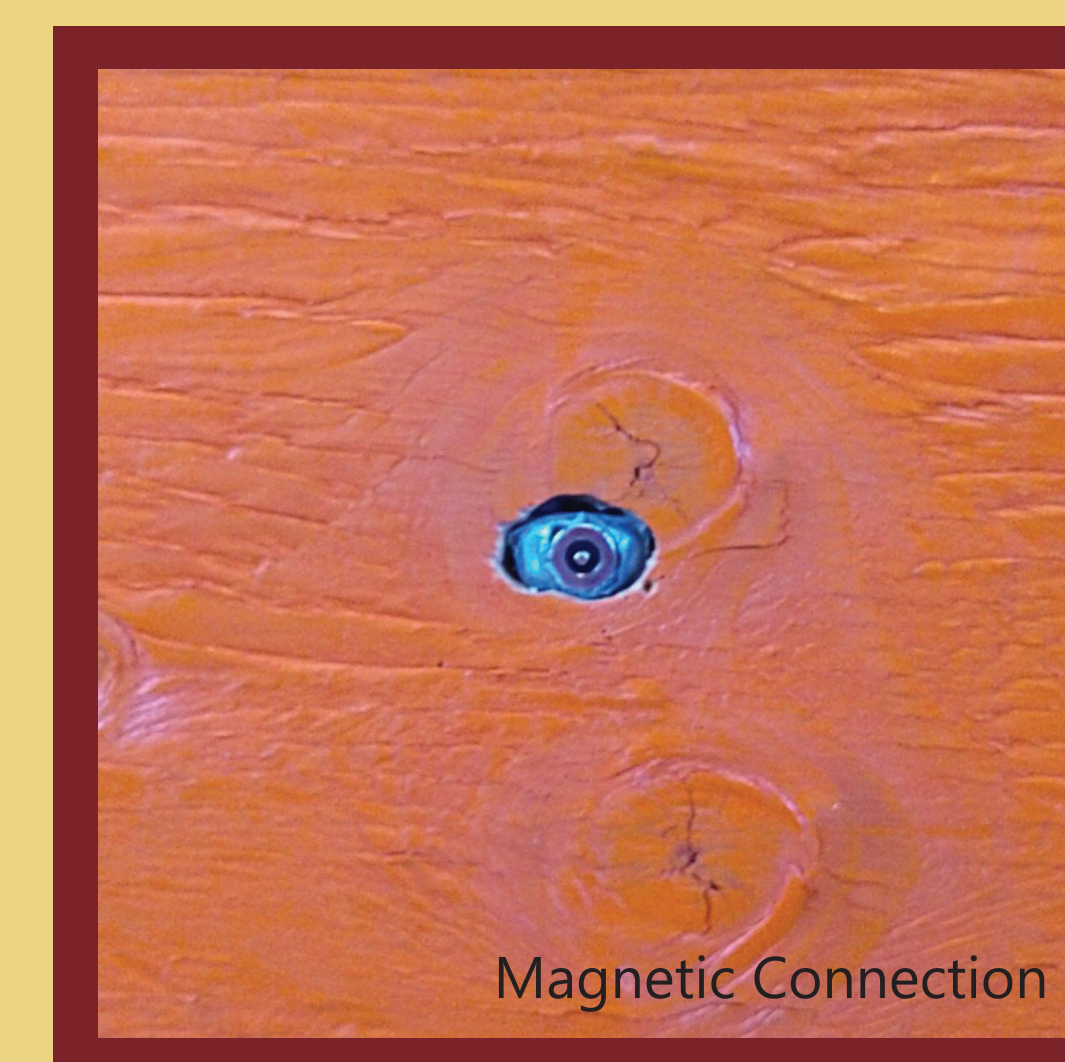
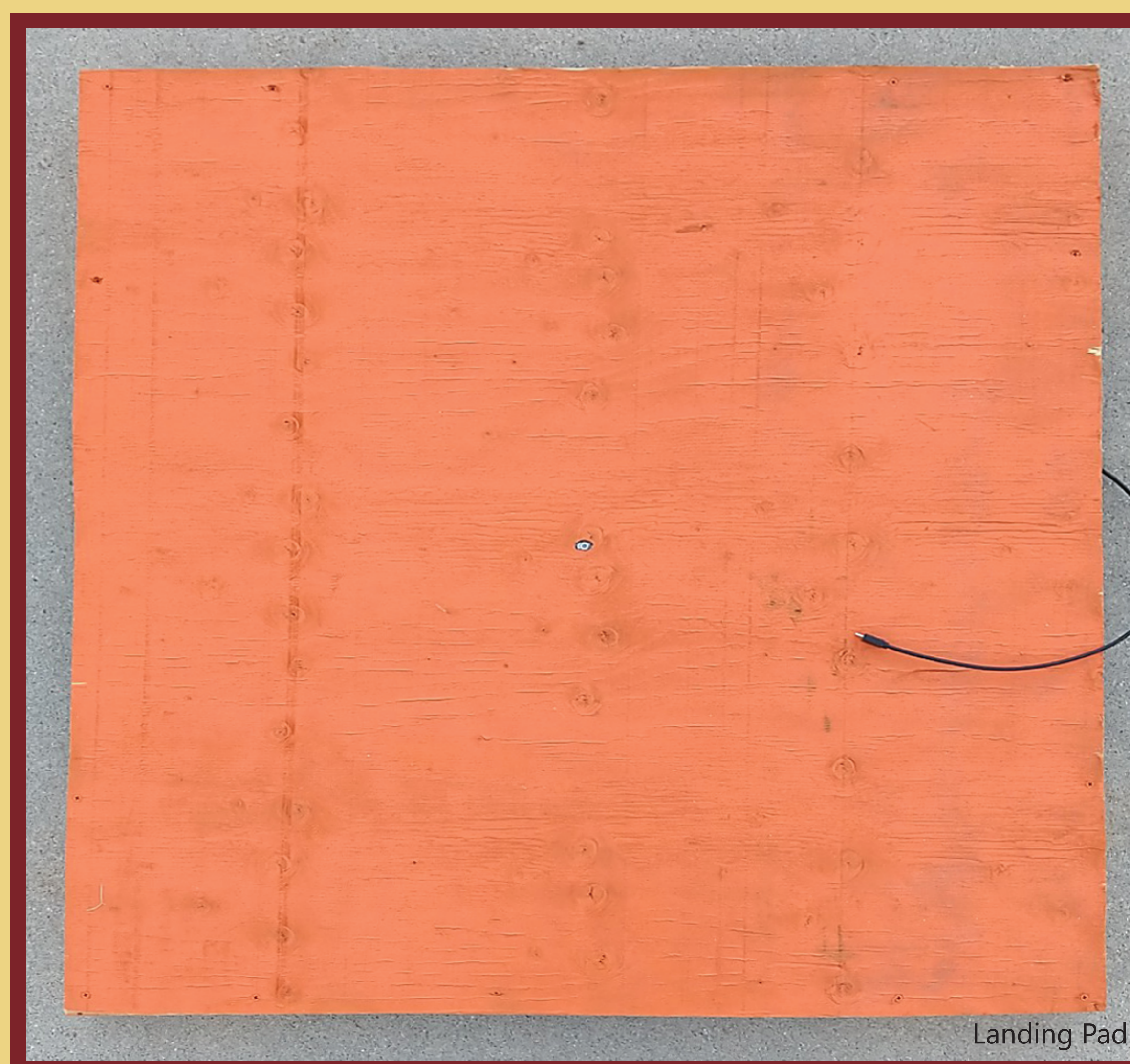
## Design Approach

### Concept Diagram



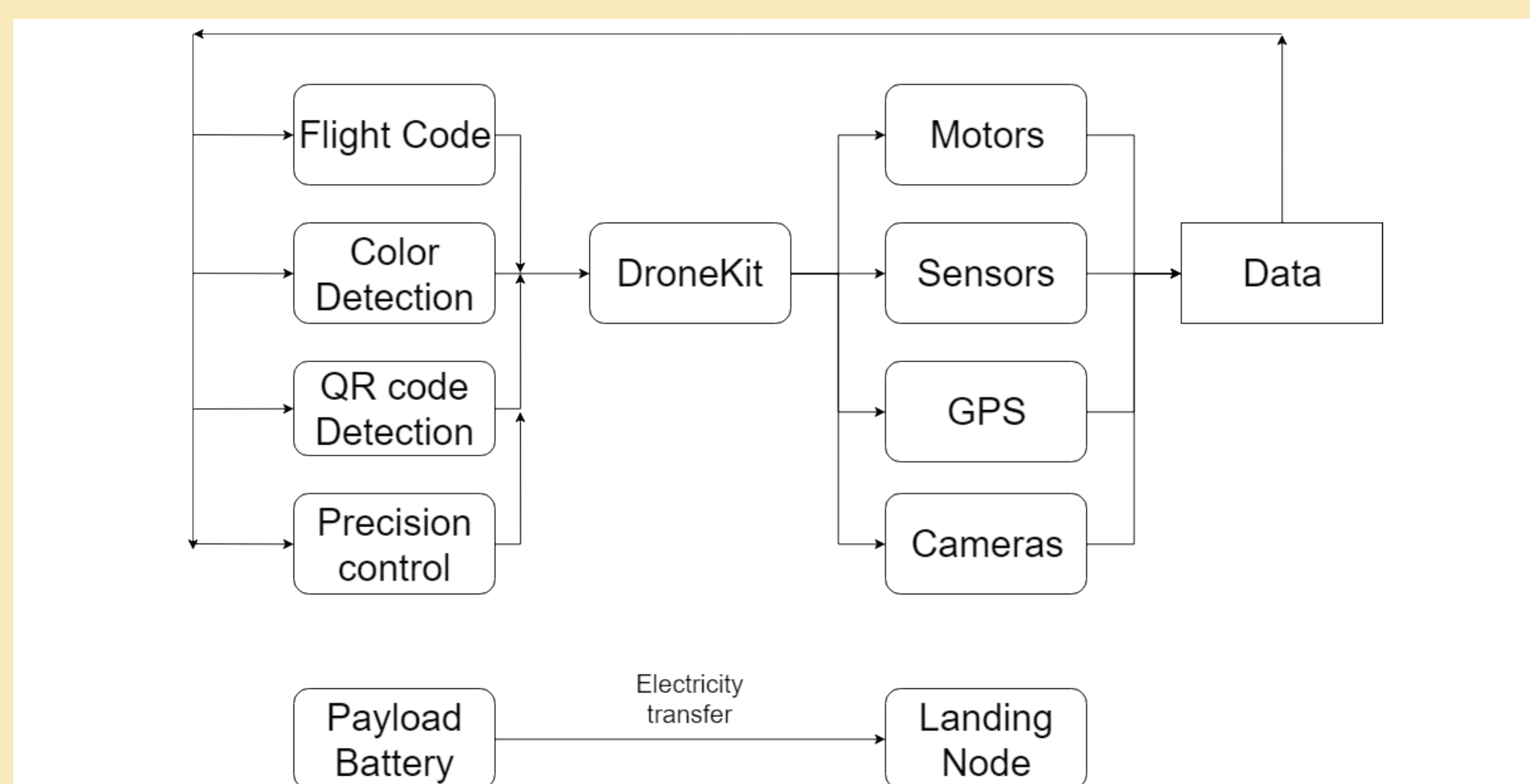
### System Implementation

- DroneKit
- Python
- Pyboof (QR)
- OpenCV2
- Lithium-ion battery
- Intel Ready-To-Fly drone
- Magnetic connection



## System Functions

### System Architecture



- Magnetic connection used for power transfer
- Software systems process data to give directives to DroneKit
- DroneKit interacts with the hardware; for example, commands propellers
- Sensors feed data back into software to complete the process

## Testing

### Unit Testing

- Fly to location
- Precision movement/landing
- QR/color detection
- Power transfer

### System Testing

- GPS coordinate testing
- Fly to location with 1 meter accuracy
- Switch flying modes
- Integration

## Conclusions

### Accomplishments

- Getting the drone to fly to location
- Reliable power transfer
- Precision movement
- Image detection/color detection/QR
- Wireless communication

### Future Extensions

- Multiple drones/devices
- Charge detection
- Server communication